

## 2. Other MPS-based algorithms

## Brief overview of other RPS-based algorithms

a) Time evolution (real/imaginary)

Can we use MPS to simulate real/maj.  
time evolution:

$$|\psi(0)\rangle \mapsto |\psi(t)\rangle = e^{-iHt} |\psi\rangle, \text{ or}$$

$$| \psi(0) \rangle \mapsto | \psi(t) \rangle = e^{-iHt} | \psi \rangle,$$

where  $| \psi(t) \rangle$  is some MPS?

## Proter expansion

Consider e.g. NN Ham.  $H = \sum \epsilon_{ij}$   
 $\uparrow$   
 N.N. terms

$$H = \sum h_i = \underbrace{\sum_{i \text{ even}} h_i}_{=: H_{\text{even}}} + \underbrace{\sum_{i \text{ odd}} h_i}_{=: H_{\text{odd}}}$$

$$e^{-iHt} = e^{-i(H_{\text{even}} + H_{\text{odd}})t}$$

$$= \left( e^{-i (H_{\text{even}} + H_{\text{odd}}) t/k} \right)^k$$

$$\approx \left( e^{-i H_{\text{even}} t/k} e^{-i H_{\text{odd}} t/k} \right)^k$$

Can get better accuracy w/  
higher-order expansion!

$$= \underbrace{\left( \prod_{i \text{ even}} e^{-i h_i t/k} \prod_{i \text{ odd}} e^{-i h_i t/k} \right)^k}_{\otimes}$$

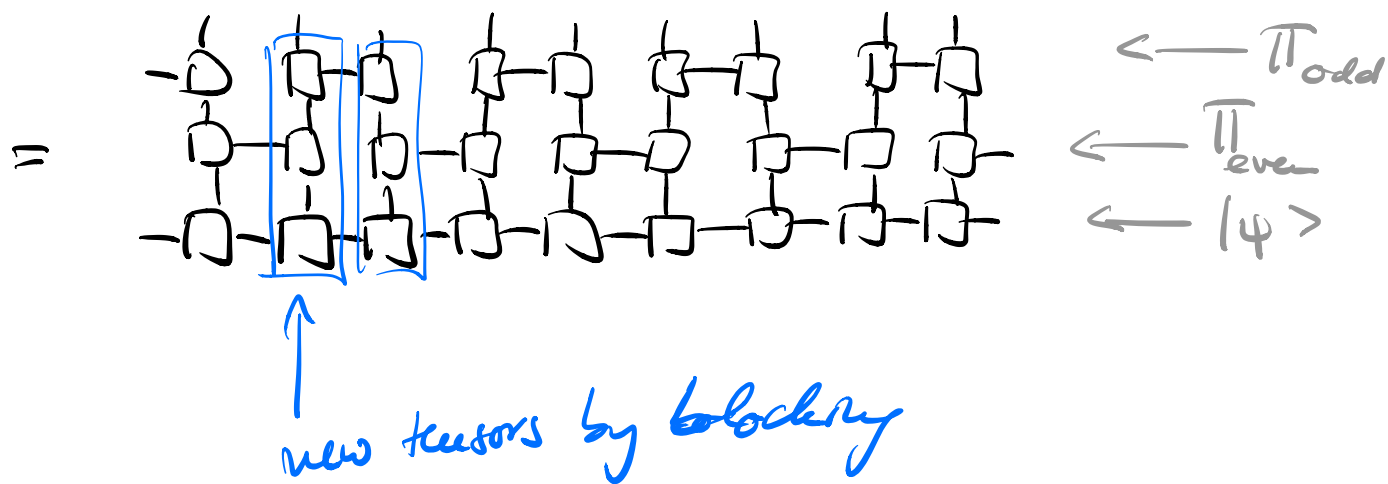
Tensor network formulation

$$e^{-i h_i t/k} = \boxed{\phantom{0000}} \leftarrow \text{operator acting on 2 sites}$$

$$= \boxed{\phantom{0000}} \text{---} \boxed{\phantom{0000}} \leftarrow \text{TN decomposition (via SVD/QR)}$$

dim.  $\chi$

$$\Rightarrow |\psi(t/k)\rangle = \left( \prod_{i \text{ even}} e^{-i h_i t/k} \prod_{i \text{ odd}} e^{-i h_i t/k} \right) |\psi(0)\rangle$$



$$= \text{---} \square \text{---} \square \text{---} \square \text{---} \square \text{---} \square \text{---} \dots$$

$\Rightarrow |\psi(t/k)\rangle$  is an MPS with an enlarged bond dimension  $D_X$ .

$\Rightarrow$  Can now use some truncation scheme (e.g. as in II.1, or by maximizing the overlap with an MPS with bond dim.  $D$  — this can be done analogous to DMRG) to get the bond dim. back to  $D$ .

Can be used as an alternative method for finding ground states, using  $|\psi\rangle \mapsto e^{-H\tau} |\psi\rangle$ ,

or for simulating true evolution.

Good: The entanglement in true evol. can grow linearly in time (i.e.,  $D$  grows exponentially in time), if initial state has finite energy density

$\Rightarrow$  simulation becomes quickly inaccurate

(can be seen from truncation error, or by evolving back again & checking for consistency).

Note: Truncation errors don't matter for many, true evol., in case we want to read the ground state!

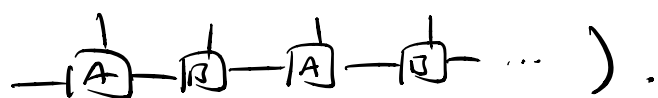
## b) Infinite systems

Can we simulate infinite systems (with a fin. Hamiltonian  $H = \sum h_i$ )?

$\underbrace{h_i}_{\text{all equal}}$

Answer: fin. MPS (possibly with large unit cell,

e.g.



- also termed iMPS ("infinite MPS") in this context.

Can again either use variational methods (as DMRG) or real/imag. time evolution methods.

### Variational methods:

iDMRG: Start with 2 sites, optimize, and add a site in the middle, which is optimized next, and so on.

No sweeps - the "old" tensors are pushed to the outside. The tensors in the

centers should converge to the iMPS tensor.

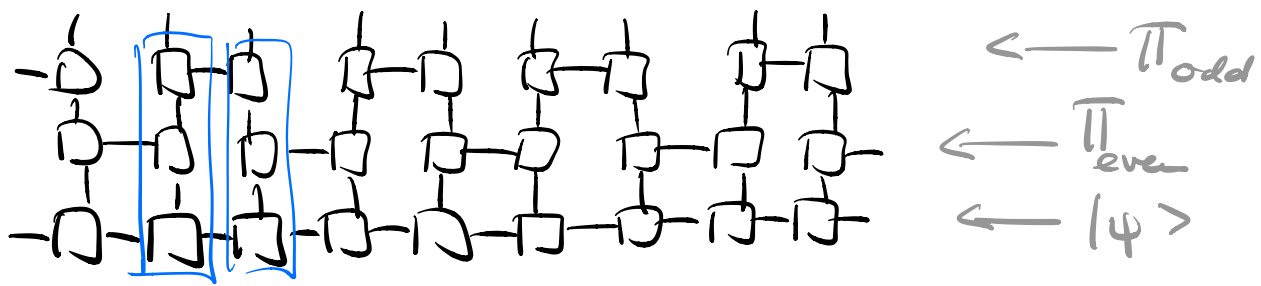
VUMPS (variational uniform MPS): Formulate the energy optimization problem directly in the tdyn. limit, by using a canonical form for the iMPS around a working site.

In essence, the problem is linearized by keeping all but the central tensor fixed - this gives a quadratic problem, which is then solved. The new tensor is updated everywhere in a neat way (respecting the canonical form).

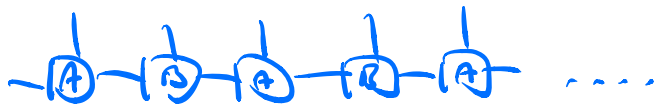
Time evolution:

TEBD (time evolving block decomposition):

Similar to the time evolution in the prev. section, but now we cut everywhere:



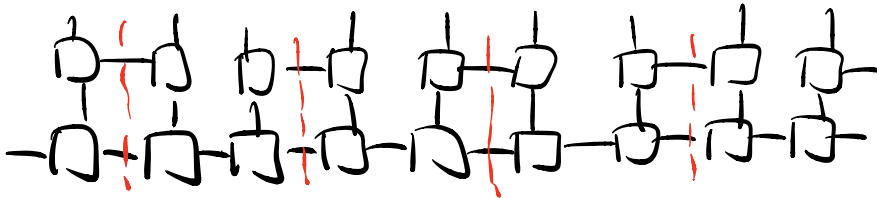
new tensors by blocking  $\leftarrow$  But: Diff. tensor on odd/even sites:



2-site unit cell!

option 1: cut everywhere

option 2: only apply 1 layer



and cut every 2nd site.

For real time evol., working in a suitable can.

form allows to determine the optimal cut locally & keep the can form: very simple

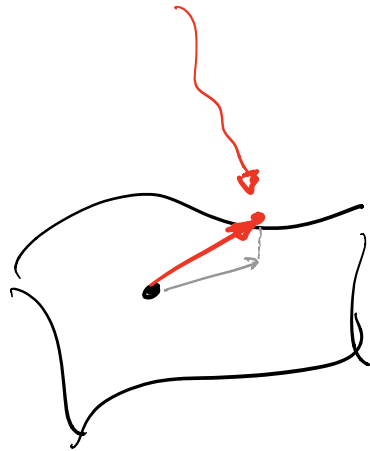
& efficient.

# TDVP (time-dependent variational principle)

Consider the space of MPS w/ bond dim.  $D$   
as a manifold.

Consider evolution

$$|\psi(t+\delta t)\rangle = e^{-iH\delta t} |\psi(t)\rangle$$



evolution leads out  
of manifold



find best projection  
back into manifold.